1	GENERIC CONTROL SYSTEM, APPARATUS	41	Proportional-Integral (P-I)
0	OR PROCESS	42	Proportional-Integral- Derivative (P-I-D)
2	.Plural processors	43	Proportional-Derivative (P-D)
3	Master-slave	44	Feed-forward (e.g., predictive)
4	Parallel	45	Combined with feedback
5	Shared memory	46	
6	Hybrid types (analog, digital)		Rate control
7	Including sequence or logic processor	47	<pre>Trainable system (e.g., self- learning, self-organizing)</pre>
8	.Cascade control	48	Neural network
9	.Supervisory control	49	Expert system
10	Of analog controllers	50	Fuzzy logic
11	.Sequential or selective	51	Statistical process control
12	State of condition or parameter		(SPC)
	(e.g., on/off)	52	Parameter estimation or
13	Position responsive		identification
14	Time responsive (duration)	53	Multiple input-multiple output
15	Having display		(MIMO) system feature (e.g.,
16	Clock-calendar (e.g., time of		decoupling)
10	day)	54	Having particular compensation
17	_		or stabilization feature
1 /	Operator interface (e.g.,	55	Filtering
1.0	display with control)	56	.Digital positioning (other than
18	Specific programming (e.g.,		machine tool)
1.0	relay or ladder logic)	57	Alignment or registration
19	Plural controlled systems,	58	Having position marking
0.0	mechanisms, or elements	59	Having optical sensing (e.g.,
20	Plural controllers	33	image projection)
21	Failure protection or	60	Support positioning (e.g.,
	reliability	00	table, stage)
22	Electrical power distribution	61	Multiple axis motion or path
23	Sequence program response	01	control
24	Addressing	62	
25	I/O table	02	Orientation (e.g., posture,
26	Diagnostics or debugging	<i>C</i> 2	pose)
27	Having status indication	63	Including velocity or
28	.Optimization or adaptive control	<i>-</i> 1	acceleration control
29	Having model	64	Position recording
30	Comparison with model (e.g.,	65	Operator control of remotely
	model reference)		located element
31	Having adjustment of model	66	Having particular position
	(e.g., update)		determining apparatue (e.g.,
32	Specific criteria of system		portable or handheld)
	performance	67	.Plural variables
33	Constraint or limit (e.g.,	68	Ratio
	max/min)	69	Positional (e.g., velocity,
34	Variable		acceleration)
35	Bidirectional (e.g.,	70	Positional with nonpositional
<i>3 3</i>	oscillatory)	71	.Specific compensation or
36	Economic (e.g., cost)		stabilization feature
37	Gain (e.g., tuning)	72	Lag (e.g., deadtime)
38		73	.Sampled data system
38 39	Having perturbation	74	Variable rate
	Test signal		
40	Plural modes		

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75	.Multiple modes (e.g., digital/	111	Worker or work station
	analog)		efficiency
76	Manual/automatic	112	Having particular work
77	Fine/coarse		transport control between
78	.Having specific error signal		manufacturing stations
	generation (e.g., up/down	113	Mobile transport
	counter)	114	Work positioning
79	.Having protection or reliability	115	Product tracking (e.g., having
	feature		product or carrier
80	Warning or alarm		identification)
81	Self-test	116	Having identification
82	Backup/standby		controlled manufacturing
83	.Having operator control		operation
	<pre>interface (e.g., control/</pre>	117	Particular manufactured product
	display console)		or operation
84	Keyboard	118	Three-dimensional product
85	Positional (e.g., joystick)		forming
86	.Having preparation of program	119	Rapid prototyping (e.g.,
87	Editing/modifying		layer-by-layer, material
88	Playback		deposition)
89	.Having specific algorithm	120	\ldots Stereolithography
90	SPECIFIC APPLICATION, APPARATUS	121	Integrated circuit production
	OR PROCESS		or semiconductor fabrication
91	.Contest or contestant analysis,	122	Continuous material having
7 -	management, or monitoring		indeterminate length (e.g.,
	(e.g., statistical analysis,		web, strand, strip, or sheet)
	handicapping, scoring)	123	Material deposition or
92	Scoring		application (e.g., spraying,
93	Probability determination or		coating)
, ,	handicapping	124	Registration control
94	.Digital audio data processing	125	Having a reference mark or
	system		pattern
95	.Product assembly or	126	Winding
, ,	manufacturing	127	Sheet making (e.g., paper
96	Integrated system (Computer		product)
50	Integrated Manufacturing (CIM)	128	Paper machine or subsystem
97	Design or planning		control
98	3-D product design (e.g.,	129	Profile analyzer or
70	solid modeling)		controller
99	Resource allocation	130	Textile
100	Job scheduling	131	Pattern design
101	_	132	For a garment
	Priority ordering	133	Having particular pattern
102	Job release determinationConstraints or rules	133	producing operation (e.g.,
103			dyeing)
104	Knowledge based (e.g., expert	134	Pattern cutting
105	system)	135	Pattern matching or
105	Rework or engineering change	133	positioning
106	Material requirement	136	Sewing
107	Bill of material	137	Having particular input data
108	Performance monitoring	101	(e.g., stitch)
109	Quality control	138	Embroidering
110	Defect analysis or	139	Spinning or winding (e.g.,
	recognition	± J /	yarn)

140	Loom control	177	Protective or diagnostic
141	Knitting	1.00	feature
142 143	Fiber preparation	178	Tool/workpiece interference
143	Having monitoring or	179	<pre>preventionTool selection/change</pre>
	<pre>inspecting (e.g., abnormality detection)</pre>	180	
1 / /	•	180	Having operator interface
144 145	Yarn quality	1.01	feature
_	Metal	181	Specific programming format
146	Casting or drawing	182	(e.g., macro)
147	<pre>Control of metallurgical property</pre>	182	Including CAD, CAM, or CIM technique
148	Rolling	183	Preset pattern
149	Having schedule adjustment	184	Machining path display
150	Control or detection of a	185	Prompting technique
	particular condition	186	Digital positioning technique
151	Speed control	187	For curve or contour
152	Tension control (e.g.,	188	Including velocity or
	interstrand)		acceleration control
153	Temperature control	189	Interpolation
154	Flatness or crown control	190	Specified tool feed path at
155	Thickness control		entry or withdrawal
156	Roll eccentricity	191	Repeated machining passes
	compensation	192	Alignment of tool or
157	Glassware forming		workpiece (e.g., origin or
158	IS (individual section)		path return)
	machine	193	Positional compensation or
159	Machining		modification compensation or
160	Having particular tool or		mod
100	tool operation	194	Coordinate transformation
161	Tracing or duplicating		technique
162	Electrical discharge	195	Having particular measuring
	machining (EDM)		device (e.g., probe)
163	3-D sculpturing using	196	Extruding
	nontracing prototype sensor	197	Molding
164	Grinding	198	Control of curing
165	Bending (e.g., press brake)	199	Vulcanization
166	Laser	200	Injection
167	Of elongated material (e.g.,	201	Plural molding machines or
10,	timber, veneer, web)		stations
168	Portable (e.g., handheld)	202	Control of temperature
169	Supervisory control (e.g.,	203	Control of pressure
	plural tools or plural	204	Monitoring, inspection, or
	processors)		control of a particular
170	Having particular control of		condition
	a motor parameter	205	Control of temperature
171	Material usage optimization	206	Pressing
172	Multiple mode (e.g., rough-	207	Heating
	<pre>finish, coarse-fine)</pre>	208	Drying
173	Adaptive (optimizing) system	209	Furnace
174	Performance monitoring	210	Multizone
175	Condition of tool or	211	Oven
	workpiece (e.g., tolerance,	212	Sintering, soldering, or
	tool wear)		bonding
176	Offsetting	213	.Article handling

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214	Article storing, retrieval, or	243	Movable (e.g., rotatable)
	arrangement (e.g.,	244	Monitoring or inspection
	warehousing, automated	245	.Robot control
	library)	246	Combined with knowledge
215	Having an identification code		processing (e.g., natural
216	Order filling		language system)
217	Article support load	247	Plural controlled devices or
	management (e.g., palletizing)		plural nonvision controlling
218	Particular charging or		devices
	discharging apparatus	248	Plural robots
219	Associating or disassociating	249	Plural processors
	plural articles	250	Specific enhancing or modifying
220	Inserting		technique (e.g., adaptive
221	Having an identification code		control)
222	Monitoring or inspection	251	Coordinate transformation
	<pre>(e.g., incomplete assembly)</pre>	252	Interpolation
223	Collating or sorting	253	Programmed data (e.g., path)
224	Having an identification code		modified by sensed data
225	Having an identification code	254	Compensation or calibration
226	Identification code determines	255	Collision prevention
	article destination	256	Overload prevention
227	Preparation of an article for	257	Based on user input
	an identification code (e.g.,	258	Having particular sensor
	<pre>printing, encoding)</pre>	259	Vision sensor (e.g., camera,
228	Having particular transport		photocell)
	between article handling	260	Having control of force
	stations	261	Having control of robot torque
229	Transport position	262	Using particular manipulator
	identification		orientation computation (e.g.,
230	Having a conveyor		vector/matrix calculation)
231	Dispensing or vending	263	Using Jacobian computation
232	Operator or payment initiated	264	Having particular operator
233	Customized dispensed article		interface (e.g., teaching box,
	(e.g., operator design)		digitizer, tablet, pendant,
234	Demonstration or duplication	0.65	dummy arm)
	of article (e.g., software,	265	.Nonreactive mixing process
025	video)		(e.g., mixing cement,
235	Printing on or of dispensed		preparing solution, diluting
226	or vended article	266	chemical)
236	Data collection or reporting	266	.Chemical process control or
227	(e.g., sales, inventory)	267	monitoring system
237	Authorization (e.g.,	268	Titration or pH level
	password, time usage limit,		Synthesis process
	personal identification number (PIN)	269	Polymerization/trimerization
238	Price adjustment	270	Distillation
239	Blending or mixing	271	Refinement or purification or
240	Condition controlled	272	rejuvenation
410	dispensing (e.g., weight or	272 273	Of fuelSeparation process
	volume)		
241	Central control of plural	274	Control of combustion or
211	dispensing units		<pre>heating apparatus (e.g., kiln, furnace, autoclave, burner,</pre>
242	Particular supply arrangement		combusion system)
	(e.g., plural sources or	275	.Mechanical control system
	compartments)	276	HVAC control
	t time of time to a	210	IVAC COIICIOI

277	Multiple zones	
278	Specific thermally responsive	
	controller	
279	Balancing or alignment	CROSS-REFERENCE ART COLLECTIONS
280	Vibration or acoustic noise control	900 SPECIAL ROBOT STRUCTURAL ELEMENT
281	Control of fluid level or volume	300 212012 3000 211000012 221100
282	Flow control (e.g., valve or	
202	pump control)	
283	Dispensing management (e.g., spraying)	FOREIGN ART COLLECTIONS
284	Irrigation	Any foreign patents or non-patent litera-
285	Fluid mixing	ture from subclasses that have been
286	.Electrical power generation or	reclassified have been transferred
	distribution system	directly to FOR Collection listed below.
287	Turbine or generator control	These collections contain ONLY foreign
288	Cogenerative system	patents or nonpatent literature. The parenthetical references in the Collection
289	Adaptive valve control	titles refer to the abolished subclasses
290	For turbine speed control	from which these Collections were derived.
291	Energy consumption or demand prediction or estimation	TIOM WHICH these corrections were derived.
292	<pre>System protection (e.g., circuit interrupter, circuit limiter, voltage suppressor)</pre>	FOR 000 CLASS-RELATED FOREIGN DOCUMENTS
293	Abnormal power, current, or	FOR 101 SEQUENTIAL OR SELECTIVE DATA
	impedance condition	PROCESSING CONROL SYSTEM,
294	Abnormal phase, waveform, or polarity condition	METHOD, OR APPARATUS (364/140) FOR 102 OPTIMIZATION OR ADAPTIVE DATA
295	<pre>Power allocation management (e.g., load adding/shedding)</pre>	PROCESSING CONTROL SYSTEM, METHOD, OR APPARATUS (364/148)
296	Time based control (e.g., real	FOR 103 DIGITAL POSITIONING (OTHER THAN
	time or duty cycle)	MACHINE TOOL) CONTROL SYSTEM,
297	Power supply regulation operation	METHOD, OR APPARATUS (364/ 167.01)
298	By voltage regulation	FOR 104 GAME OR AMUSEMENT (364/410)
299	.Specific application of	FOR 105 .Scoring (364/411)
	temperature responsive control system	FOR 106 .Wagering (364/412)
300	For heating or cooling	
301	.Specific application of pressure responsive control system	
302	.Specific application of positional responsive control system	
303	.Specific application of dimensional responsive control system	
304	.Specific application of speed responsive control system	
305	.Specific application of weight	
	responsive control system	
306	.Specific application of control	
	based on elapsed time	

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